Robot Specification of Team ZJUDancer

- Robot picture

- Robot name

   ZJUDancer
- Height of the robot

   680mm
- Weight of the robot

   4.7kg
- Walking speed in cm/s

   30cm/s
- Number of degrees of freedom and type of motors on each kinematic chain of the robot

   There are 18 degrees of freedom in ZJUDancer robot.

   Dynamixel MX-106, MX-64 and MX-28 servo.
- Type of sensors used(incl. type of camera(s))

   The type of camera is UI-1221LE-C-HQ.

   The type of IMU is ADIS16405BMLZ.

   The type of feet force sensor is CZL-YB-46B/10kg.
- Computing unit(s)

   The computing unit is NVIDIA Jetson TX2 board.