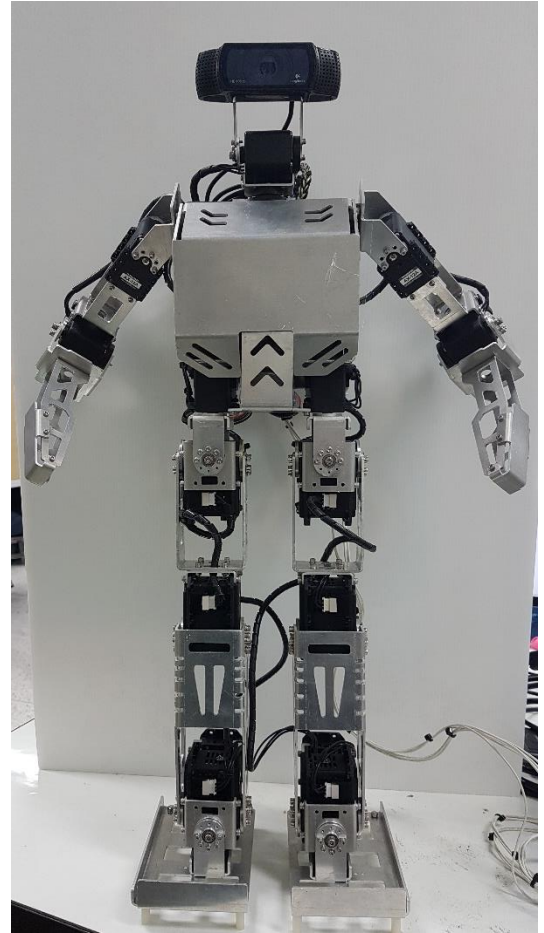


Robot Specification

Team Hanuman-KMUTT

Robot model	1
Robot amount	3
Height	57 cm
Weight	4 kg
Walking speed	~30 cm/s
Sensor	MPU-6500 (3-axis gyroscope 3-axis accelerometer)
DOF	20
Motor type	8 Robotis AX-12 6 Robotis MX-28 6 Robotis Mx-64
Camera	Logitech c920
Computing unit	ODROID-C1+ STM32F411RE



Robot model	2
Robot amount	2
Height	47 cm
Weight	3.5 kg
Walking speed	~25 cm/s
Sensor	MPU-6500 (3-axis gyroscope 3-axis accelerometer)
DOF	20
Motor type	8 Robotis AX-12 12 Robotis MX-28
Camera	Logitech quickcam pro
Computing unit	ODROID-C1+ STM32F411RE

